

Dynamic Multiple-Message Broadcast: Bounding Throughput in the Affectance Model

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Introduction

Dynamic Multiple-Message Broadcast (MMB) [1]:

- *problem*: packets arrive at nodes **continuously**, to be delivered to **all** nodes
- *metric*: **competitive throughput** of deterministic distributed MMB algorithms
- *analysis*: in **general Affectance model**:
 - Affectance subsumes many communication-interference models
e.g. RN and SINR models
 - conceptual idea: parameterize interference from transmitting nodes into links
 - introduced [2,3,4] for link scheduling as link-to-link affectance

[1] (non-dynamic MMB) Khabbazian-Kowalski PODC 2011

[2] Halldórsson-Wattenhofer, ICALP 2009

[3] Kesselheim, PODC 2012

[4] Kesselheim-Vöcking, DISC 2010

Introduction

- Contributions:
 - we introduce new model characteristics:
(based on comm network, affectance function, and a chosen BFS tree)
 - **maximum average tree-layer affectance K**
 - **maximum fast-paths affectance M**
 - we show how characteristics influence broadcast time complexity:
if one uses a specific BFS tree (GBST [1]) that minimizes $M(K + M)$
single broadcast can be done in time $D + O(M(K + M) \log^3 n)$
 - we extend this to dynamic packet arrival model and the MMB problem:
new algorithm reaching throughput of $\Omega(1/(\alpha K \log n))$
 - ... also simulations for RN

[1] Gąsieniec-Peleg-Xin, DC 2007

Introduction

- Observations:
 - throughput measured in the limit \Rightarrow
preprocessing is free \Rightarrow protocol is distributed
 - deterministic results are existential (protocol includes randomized subroutine)
 - can also be applied to mobile networks,
if movement is slow enough to recompute structure
 - To the best of our knowledge,
first work on dynamic MMB under the general Affectance model

The General Affectance Model

Interference:

- 1-hop:
 - Radio Network model without collision detection
- (≥ 1)-hop:
 - value $a_u(\ell) \leq 1$ quantifies interference of node u on link ℓ
 - $a_u((u, v)) = 0$, $a_v((u, v)) = 1$, and $a_w((u, v)) = 1$, $w \in N(v)$ and $w \neq u$
 - $a.(\cdot)$ is any function s.t. $a_{\{u,v\}}(\ell) = a_{\{u\}}(\ell) + a_{\{v\}}(\ell)$
 - affectance degradation parameter α

Successful transmission:

- transmission from u is received at v iff
 - u transmits
 - v listens
 - $a_T((u, v)) < 1$, where $T = \{\text{set of nodes transmitting}\}$

Injection and Performance Metric

Feasible adversarial injections: \exists OPT with bounded packet latency.

At most 1 packet may be received by a node in each time slot
and all nodes must receive the packet in order to be delivered
 \Rightarrow feasible adversarial injection rate at most 1 packet per time slot.

Performance metric: competitive throughput in the limit

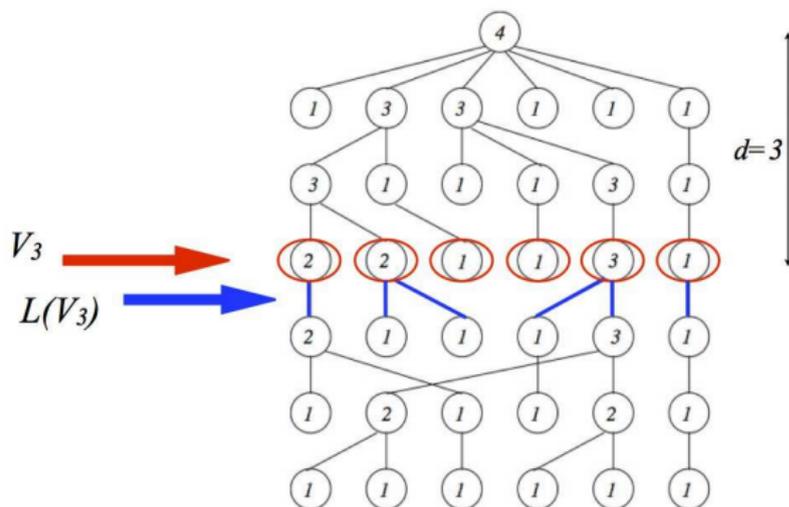
$$\exists f : \lim_{t \rightarrow \infty} \frac{d_{ALG}(t)}{d_{OPT}(t)} \in \Omega(f)$$

Affectance Characterization

Maximum average tree-layer affectance

Quantifies the difficulty to disseminate from one layer to the next one.

$$K(T, s) = \max_d \max_{V' \subseteq V_d(T)} \frac{a_{V'}(L(V'))}{|L(V')|}$$

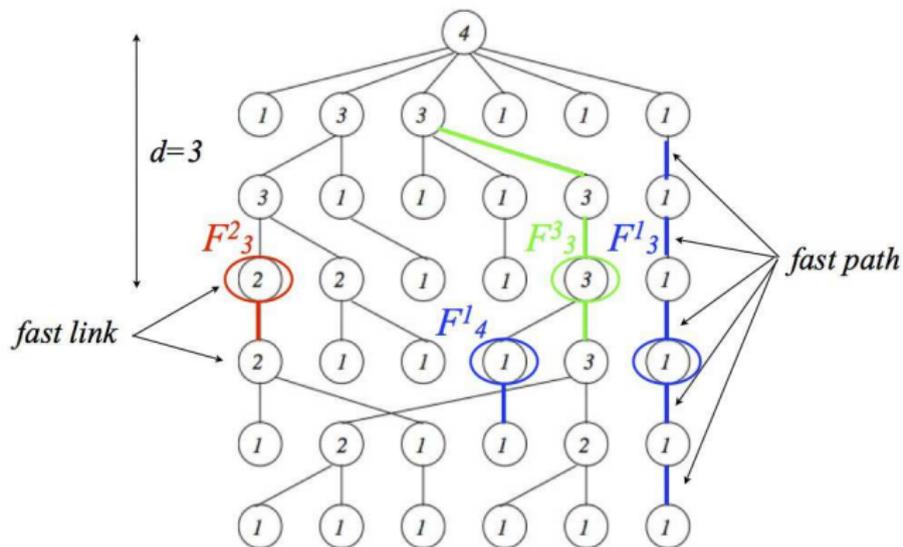


Affectance Characterization

Maximum fast-paths affectance

Quantifies the difficulty for dissemination on a path due to other paths.

$$M(T, s) = \max_{d,r} \max_{\ell \in F_d^r(T)} a_{F_d^r(T)}(\ell)$$



Low-Affectance Broadcast Spanning Tree (LABST)

- Tree construction:

- 1 $T_{\min} \leftarrow \arg \min_{T \in \text{GBST}(s)} M(T, s)(M(T, s) + K(T, s))$

- 2 $T_{\min} \rightsquigarrow \text{LABST } T$

T avoids links between nodes of the same rank with big affectance
blowing up GBST ranks by a $M(T)$ multiplicative factor

- Broadcast schedule: defined using the ranks in T

Low-Affectance Broadcast Spanning Tree (LABST)

Corollary

For any given network of $n \geq 8$ nodes and source s , diameter D , and affectance degradation distance $\lceil \log n \rceil$, there exists a broadcasting schedule of length

$$D + O(M(T_{\min}, s)(M(T_{\min}, s) + K(T_{\min}, s)) \log^3 n)$$

For comparison, in Radio Networks: $D + O(\log^3 n)$ [1]
 $O(D + \log^2 n)$ [2]

[1] Gąsieniec-Peleg-Xin, DC 2007

[2] Kowalski-Pelc, DC 2007

MMB Protocol

- define LABST from each source node
 - define a MBTF [1] list of source nodes
 - assign a token to some source node from list
- 1 upon receiving the token at node s
 - 2 if $queue(s)$ is “empty”:
 - 1 pass token to next in list
 - 3 else if $queue(s)$ is “small”:
 - 1 disseminate Δ packets pipelined with period δ
 - 2 pass token to next in list
 - 4 else if $queue(s)$ is “big”:
 - 1 move s to front of list
 - 2 while $queue(s)$ is “big”: disseminate Δ packets pipelined with period δ
 - 3 pass token to next in list

[1] Chlebus-Kowalski-Rokicki 2009

MMB Protocol Analysis

Lemma

There exists a MMB protocol that achieves a throughput ratio of at least

$$\lim_{t \rightarrow \infty} \frac{1}{1 + \delta} - \frac{2\Delta n^2}{t}$$

Corollary

For any given network of n nodes, diameter D , affectance degradation distance α , and $K = \max_{s \in S} K(T_{\min}(s), s)$, there exists a MMB protocol such that the throughput ratio converges to

$$\frac{1}{O(\alpha K \log n)}$$

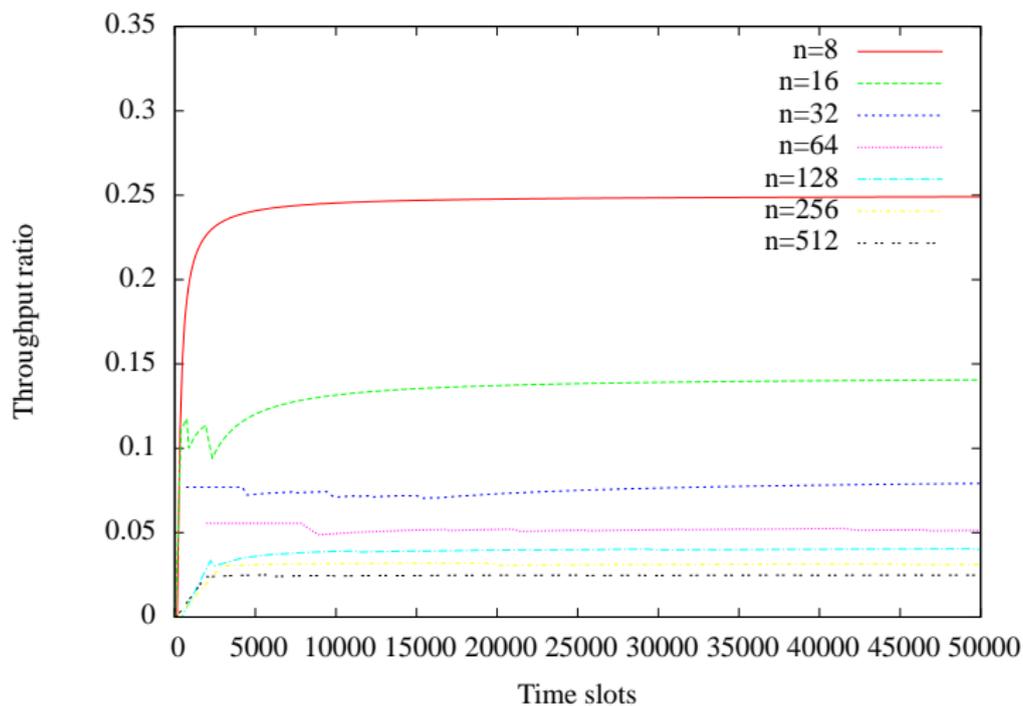
For comparison, in Radio Networks:

- using WEB protocol [1] for propagation converges to $1/O(\log^2 n)$
- $O(1/\log n)$ for any single-instance MMB algorithm [2]

[1] Chlamtac-Weinstein 1987

[2] Ghaffari-Haeupler-Khabbazian 2013

Simulations



Thank you