

Assessment of Implicit Implementation of the AUSM⁺ Method and the SST Model for Viscous High Speed Flow



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Introduction

- Aerodynamic and thermal environment predictions for high speed vehicles are essential in design and development
- CFD methods have gained significant prominence in recent years

Muylaert J. and W. Berry, 1998. ESA bulletin 96

- A number of challenges remains, including:
 - 1. devising accurate and robust numerical schemes for the convective flux computation of Navier-Stokes solvers
 - 2. turbulent flow modelling







Current work

- An analytical Jacobian for the AUSM⁺ scheme has been implemented into a fully implicit solver
- A description of the derivation procedure will be given along with a ۲ brief evaluation of the performance of the formulation
- As examples of aerospace interest:



Single Cone

Infinite Cylinder



Ramp SWBLI

Orion CEV

For the turbulent cases the SST turbulence model of Menter has been used





HMBv2

- Finite volume spatial discretisation
- Fully un-factored implicit time discretisation
- GCG/ILU(0) linear system solver



- Used successfully for a wide range of aerospace applications including low Mach, subsonic and transonic flows [1], [2]
- Generally employs the Roe or Osher schemes
- In the present work, the AUSM⁺ scheme has been implemented for high Mach number flows



- [1] Lawson, S.-J., R. Steijl, M. Woodgate, and G.N. Barakos. 2012. High Performance Computing for Challenging Problems in Computational Fluid Dynamics. *Progress in Aerospace Science*, 52:19–29
- [2] Barakos, G.N., R. Steijl, A. Brocklehurst, and K. Badcock. 2005. Development of CFD Capability for Full Helicopter Engineering Analysis. *31st European Rotorcraft Forum*



The AUSM⁺ scheme

Introduced by M.-S. Liou ref. [3]:

- Formulated to guarantee the enthalpy preservation and resolve contact discontinuities
- Capable of solving flow fields at a wide range of Mach numbers; perform reasonably well for high speed flows

Compared to the Roe scheme is shown to be less prone to shock anomalies [4], and in better agreement with experimental data [5]

- [3] Liou, M.-S. 1996. A Sequel to AUSM: AUSM⁺. Journal of Computational Physics, 129:364–382.
- [4] Kitamura, K., E. Shima, and P.L. Roe. 2012. Carbuncle Phenomena and Other Shock Anomalies in Three Dimensions. *AIAA Journal*, 50(12):2655–2669.
- [5] Darracq, D., S. Campagneux, and A. Corjon. 1999. Computation of Unsteady Turbulent Airfoils Flows with an Aeroelastic AUSM+ Implicit Solver. *16th AIAA Applied Aerodynamics Conference*.





The inviscid flux is split into mass flow and pressure terms

$$\mathbf{f}_{i-1/2} = \dot{m}_{1/2} \mathbf{P} + \mathbf{p}_{1/2}$$
(1)

where with an up-winding approach

$$\mathbf{P} = \left\{ \mathbf{P}_{L} \quad \text{if } \dot{m}_{1/2} > 0; \quad \mathbf{P}_{R} \quad \text{otherwise} \right\} = \left(1, u, H\right)^{\mathrm{T}} \quad (2)$$

and

$$\mathbf{p}_{1/2} = (0, p_{1/2}, 0)^{\mathrm{T}}$$
(3)

$$\dot{m}_{1/2} = a_{1/2} M_{1/2} \{ \rho_L \text{ if } M_{1/2} > 0; \rho_R \text{ otherwise } \}$$
 (4)



Following the flux-splitting idea

$$M_{1/2} = M_{(4)}^{+}(M_{L}) + M_{(4)}^{-}(M_{R})$$
(5)

$$p_{1/2} = P_{(5)}^{+}(M_L)p_L + P_{(5)}^{-}(M_R)p_R$$
(6)

the superscripts "+" and "-" are associated with the right and left waves and

$$M_{L} = \frac{u_{n,L}}{a_{1/2}} \qquad M_{R} = \frac{u_{n,R}}{a_{1/2}}$$
(7)

a common speed of sound has to be defined to evaluate the Mach numbers

$$a_{1/2} = min(\widehat{a}_{L}, \widehat{a}_{R}); \quad \widehat{a}_{L} = a_{L}^{*2} / max(a_{L}^{*}, u_{n,L}), \quad \widehat{a}_{R} = a_{R}^{*2} / max(a_{R}^{*}, -u_{n,R}) \quad (8)$$

where

$$a_{L/R}^{*2} = \frac{2(\gamma - 1)}{\gamma + 1} H_{L/R}$$
(9)









Fully un-factored implicit solver

In a fully un-factored approach the new time level is introduced simultaneously for all the cells

$$\frac{d}{dt}(\mathbf{W}_{i,j,k}V_{i,j,k}) = -\mathbf{R}_{i,j,k}(\mathbf{W}) \longrightarrow \left[\frac{V_{i,j,k}}{\Delta t^*}\frac{\partial \mathbf{W}_{i,j,k}}{\partial \mathbf{P}_{i,j,k}} + \frac{\partial \mathbf{R}_{i,j,k}}{\partial \mathbf{P}_{i,j,k}}\right] \Delta \mathbf{P}_{i,j,k} = -\mathbf{R}_{i,j,k}(\mathbf{W}^m)$$

The system of linear equation can be solved, by mean of a Krylov subspace method, as example the GCG method

The efficiency of Krylov-subspace methods depends strongly on the preconditioning which has the purpose to cluster the eigenvalues of the system matrix around unity \longrightarrow ILU(0)







A Jacobian matrix for the AUSM⁺ scheme

Derivative of equation (1)

$$\mathbf{f}_{i-1/2} = \dot{m}_{1/2} \mathbf{P} + \mathbf{p}_{1/2}$$
 (1)

$$\frac{\partial \mathbf{f}_{i-\frac{1}{2}}}{\partial \mathbf{P}_{L/R}} = \frac{\partial \dot{m}_{1/2}}{\partial \mathbf{P}_{L/R}} \mathbf{P} + \dot{m}_{1/2} \frac{\partial \mathbf{P}}{\partial \mathbf{P}_{L/R}} + \frac{\partial \mathbf{p}_{1/2}}{\partial \mathbf{P}_{L/R}}$$

From equations (3) and (4) it is clear that, if

 $\mathbf{P}_{1/2} = (0, p_{1/2}, 0) \tag{3}$

 $\dot{m}_{1/2} = a_{1/2} M_{1/2} \{ \rho_L \text{ if } M_{1/2} > 0; \rho_R \text{ otherwise } \}$ (4)

$$\frac{\partial a_{1/2}}{\partial \mathbf{P}_{L/R}}$$
; $\frac{\partial M_{1/2}}{\partial \mathbf{P}_{L/R}}$; and $\frac{\partial p_{1/2}}{\partial \mathbf{P}_{L/R}}$

are known, the evaluation of the inviscid flux contributions to the full Jacobian matrix is straighforward







Derivative of the interface speed of sound

The interface speed of sound definition is critical in the AUSM⁺

$$a_{1/2} = \min(\widehat{a}_{L}, \widehat{a}_{R}); \quad \widehat{a}_{L} = a_{L}^{*2} / \max(a_{L}^{*}, u_{n,L}), \quad \widehat{a}_{R} = a_{R}^{*2} / \max(a_{R}^{*}, -u_{n,R})$$
(8)

Differentiating expression (8), the presence of the min/max operators leads to a dual formulation when:

$$\widehat{a}_{L} = \widehat{a}_{R}$$
$$a^{*}_{L/R} = \pm u_{n,L/R}$$

Indeed, the interface speed of sound is a discountinuous function





At the points of discontinuity, we consider the interface speed of sound derivative as the average of the left and right limits





$$\frac{\partial a_{1/2}}{\partial \mathbf{P}_{L/R}} = \longrightarrow \quad \text{for } \widehat{a_L} = \widehat{a_R} \quad \begin{cases} \frac{1}{2} \frac{\partial}{\partial \mathbf{P}_{L/R}} \left(a_L^* + a_R^*\right) & \text{if } a_L^* > u_{n,L} \& a_R^* > -u_{n,R} \\ \frac{1}{2} \frac{\partial}{\partial \mathbf{P}_{L/R}} \left(\frac{a_L^{*2}}{u_{n,L}} + \frac{a_R^{*2}}{-u_{n,R}}\right) & \text{if } \frac{a_L^{*2}}{u_{n,L}} = \frac{a_R^{*2}}{-u_{n,R}} \\ \frac{1}{2} \frac{\partial}{\partial \mathbf{P}_{L/R}} \left(a_L^* + \frac{a_R^{*2}}{-u_{n,R}}\right) & \text{if } a_L^* = \frac{a_R^{*2}}{-u_{n,R}} \\ \frac{1}{2} \frac{\partial}{\partial \mathbf{P}_{L/R}} \left(\frac{a_L^{*2}}{u_{n,L}} + a_R^*\right) & \text{if } a_L^* = \frac{a_R^{*2}}{-u_{n,R}} \end{cases}$$





Derivative of the interface Mach number

From equation (5)

$$\frac{\partial M_{1/2}}{\partial \mathbf{P}_{L/R}} = \frac{\partial M_{(4)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} + \frac{\partial M_{(4)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}}$$

The derivative of the interface Mach number polynomials can be directly obtained from equation (10)

$$\frac{\partial M_{(4)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} = \begin{cases} \frac{\partial M_{(1)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} & \text{if } |M_{L}| \ge 1 \\ \frac{\partial M_{(2)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} (1 + 16\beta M_{(2)}^{-}(M_{L})) - 16\beta M_{(2)}^{+}(M_{L}) \frac{\partial M_{(2)}^{-}(M_{L})}{\partial \mathbf{P}_{L/R}} & \text{otherwise} \end{cases}$$

$$\frac{\partial M_{(4)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} = \begin{cases} \frac{\partial M_{(1)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} & \text{if } |M_{R}| \ge 1 \\ \frac{\partial M_{(2)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} (1 + 16\beta M_{(2)}^{+}(M_{R})) + 16\beta M_{(2)}^{-}(M_{R}) \frac{\partial M_{(2)}^{+}(M_{R})}{\partial \mathbf{P}_{L/R}} & \text{otherwise} \end{cases}$$



and (12)

$$\frac{\partial M_{(1)}^{\pm}(M_{L/R})}{\partial \mathbf{P}_{L/R}} = \pm \frac{1}{2} \left(\frac{\partial M_{L/R}}{\partial \mathbf{P}_{L/R}} \pm \frac{\partial |M_{L/R}|}{\partial \mathbf{P}_{L/R}} \right) ; \qquad \frac{\partial M_{(2)}^{\pm}(M_{L/R})}{\partial \mathbf{P}_{L/R}} = \pm \frac{1}{2} (M_{L/R} \pm 1) \frac{\partial M_{L/R}}{\partial \mathbf{P}_{L/R}}$$

where

$$\frac{\partial M_L}{\partial \mathbf{P}_{L/R}}$$
, $\frac{\partial |M_L|}{\partial \mathbf{P}_{L/R}}$, $\frac{\partial M_R}{\partial \mathbf{P}_{L/R}}$ and $\frac{\partial |M_R|}{\partial \mathbf{P}_{L/R}}$

can be easily obtained from equation (7) knowing the interface speed of sound and the cell-face normal velocity derivatives

Note:

$$\frac{\partial M_{(4)}^{\pm}}{\partial P_{L/R}} = M'_{(4)}^{\pm}(M) \frac{\partial M}{\partial P_{L/R}}$$

the interface Mach polynomials and the relative derivatives are continuous functions





Derivative of the pressure flux

From equation (6)

$$\frac{\partial p_{1/2}}{\partial \mathbf{P}_{L/R}} = \frac{\partial P_{(5)}^{+}(M_L)}{\partial \mathbf{P}_{L/R}} p_L + \frac{\partial P_{(5)}^{-}(M_R)}{\partial \mathbf{P}_{L/R}} p_R + P_{(5)}^{+}(M_L) \frac{\partial p_L}{\partial \mathbf{P}_{L/R}} + P_{(5)}^{-}(M_R) \frac{\partial p_R}{\partial \mathbf{P}_{L/R}}$$

and eq. (12)

$$\frac{\partial P_{(5)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} = \begin{cases} \frac{1}{M_{L}} \frac{\partial M_{(1)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} - \frac{M_{(1)}^{+}(M_{L})}{M_{L}^{2}} \frac{\partial M_{L}}{\partial \mathbf{P}_{L/R}} & \text{if } |M_{L}| \geq 1 \\ \frac{\partial M_{(2)}^{+}(M_{L})}{\partial \mathbf{P}_{L/R}} (2 - M_{L} - 16\alpha M_{L} M_{(2)}^{-}(M_{L})) - & \text{otherwise} \\ M_{(2)}^{+}(M_{L}) \left(\frac{\partial M_{L}}{\partial \mathbf{P}_{L/R}} + 16\alpha (M_{L} \frac{\partial M_{(2)}^{-}(M_{L})}{\partial \mathbf{P}_{L/R}} + M_{(2)}^{-}(M_{L}) \frac{\partial M_{L}}{\partial \mathbf{P}_{L/R}}) \right) \end{cases}$$





$$\frac{\partial P_{(5)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} = \begin{cases} \frac{1}{M_{R}} \frac{\partial M_{(1)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} - \frac{M_{(1)}^{-}(M_{R})}{M_{R}^{2}} \frac{\partial M_{R}}{\partial \mathbf{P}_{L/R}} & if |M_{R}| \ge 1 \\ \frac{\partial M_{(2)}^{-}(M_{R})}{\partial \mathbf{P}_{L/R}} (-2 - M_{R} + 16\alpha M_{R} M_{(2)}^{+}(M_{R})) - \\ \frac{\partial M_{(2)}^{-}(M_{L})}{\partial \mathbf{P}_{L/R}} (-2 - M_{R} + 16\alpha (M_{R} M_{(2)}^{+}(M_{R}))) - \\ M_{(2)}^{-}(M_{L}) \left(\frac{\partial M_{R}}{\partial \mathbf{P}_{L/R}} - 16\alpha (M_{R} \frac{\partial M_{(2)}^{+}(M_{R})}{\partial \mathbf{P}_{L/R}} + M_{(2)}^{+}(M_{R}) \frac{\partial M_{R}}{\partial \mathbf{P}_{L/R}}) \right) \end{cases}$$

Note:

$$\frac{\partial P_{(5)}^{\pm}}{\partial P_{L/R}} = P'_{(5)}^{\pm}(M) \frac{\partial M}{\partial P_{L/R}}$$

also the pressure flux polynomials are continuous functions and so are their derivatives







Comparison of the AUSM⁺ and Roe schemes

Test case: inviscid flow around a single cone with blunt nose



- AUSM⁺ showed the best agreement with the theory and the correlation results
- The shock predicted by the AUSM⁺ is less spurious unlike the Roe scheme, especially around the stagnation point

[6] Billing, F.S. 1967. Shock-Wave Shapes Around Spherical- and Cylindrical-Nosed Bodies. *Journal of Spacecraft and Rockets*, 4:822–834.



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Performance of the implicit scheme

Test cases:

- Inviscid flow around a infinite cylinder
- Laminar (Re=10⁵) flow around the ORION spacecraft

Note: the following norm-of-the-error has been used

$$log\left(\frac{L_2(Res. t > 0)}{L_2(Res. t = 0)}\right)$$





- The analytical Jacobian leads to a solver that is about two times faster than with the numerical Jacobiab
- Compared to the 4-stage Runge Kutta it is 30% and 40% faster
- A comparison of the time needed to obtain a convergent solution with:

RK4, CFL=0.9 RK4 till -1 (-2) and then the implicit scheme, CFL=2.5 (3,0)

confirms that the implicit approach is 30 - 40% faster than the explicit one





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(a) Infinite cylinder, inviscid flow.

For both Mach 3 and 5, and grid refinements, the solver can run at CFL numbers equal and often higher than with the numerical Jacobian

The implicit scheme allows to run at least CFL numbers around 2.5 also in presence of the strong shocks, expansions and interactions characterising the flow field around the Orion.





Shock-wave/ turbulent boundary-layer interaction test case

- In [13] shock-wave/boundary-layer interactions, generated using two-dimensional compression ramps, were studied experimentally. The characteristics of the incoming boundary layer were $\delta = 24$ mm, $M_{\infty} = 2.84$, Re = 6.5 x 10 7 m⁻¹
- The numerical solutions fit reasonably the experimental data. Indeed, the SST model and the AUSM + scheme are able to capture the recirculation zones with a reasonable level of reliability.



[13] Muck, K.-C., J. Andreopoulos, and J.-P. Dussauge. 1988. Unsteady Nature of Shock-Wave/Turbulent Boundary- Layer Interaction. AIAA Journal, 26(2):179–187.



Orion CEV aerodynamic testing



[14] Murphy, K.J., et al. 2011. Orion Crew Module Aerodynamic Testing. In: 29th AIAA Applied Aerodynamics Conference.



Conclusions and Future Works

- The derivation of a fully analytical Jacobian for the AUSM⁺ has been presented
- The implicit scheme with the analytical Jacobian has been tested resulting to be faster than the same implicit scheme with a numerically approximate Jacobian and the explicit 4-stage Runge-Kutta method
- The results, compared to experimental data, showed that the SST model and the AUSM⁺ can cope with a wide range of high speed test cases with a good level of reliability
- Additional improvements are still possible and further investigations will be conducted to evaluate possible simplifications that can be made to the analytical Jacobian
- The AUSM⁺-family fluxes will represent the basis for the continuum part in a hybrid continuum/kinetic Boltzmann method for partially rarefied flow





Thank you



